

International service hotline
400-852-9898

Shenzhen Han's Robot Co., Ltd.
Headquarters address: 6/F, Building 3, Han's Laser
Global Intelligent Manufacturing Industry Base,
Bao'an District, Shenzhen
cobot@hanslaser.com



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Shenzhen Han's Robot Co., Ltd.
www.hansrobot.com

Catalog

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Company Profile



Vision

To be the global leader
in the era of intelligent
robots

Mission

Serve humanity with
robot technology

Values

Lead, fast-speed, service,
sharing, passion,
enthusiasm, curiosity

Shenzhen Han's Robot Co., Ltd., invested and established by Han's Laser Technology Group (stock name: Han's Laser, stock code: 002008), is a high-tech enterprise established on the basis of the Robot Division from Han's Motor. It was founded in August, 2017 with its headquarter and production base located in Han's Laser global intelligent manufacturing base, Bao'an District, Shenzhen, with subsidiaries in Tianjin city and Germany. Han's Robot is dedicated to the development, promotion and application of intelligent robots in industry, healthcare, logistics, services and so on, becoming the global leader in the era of intelligent robots.

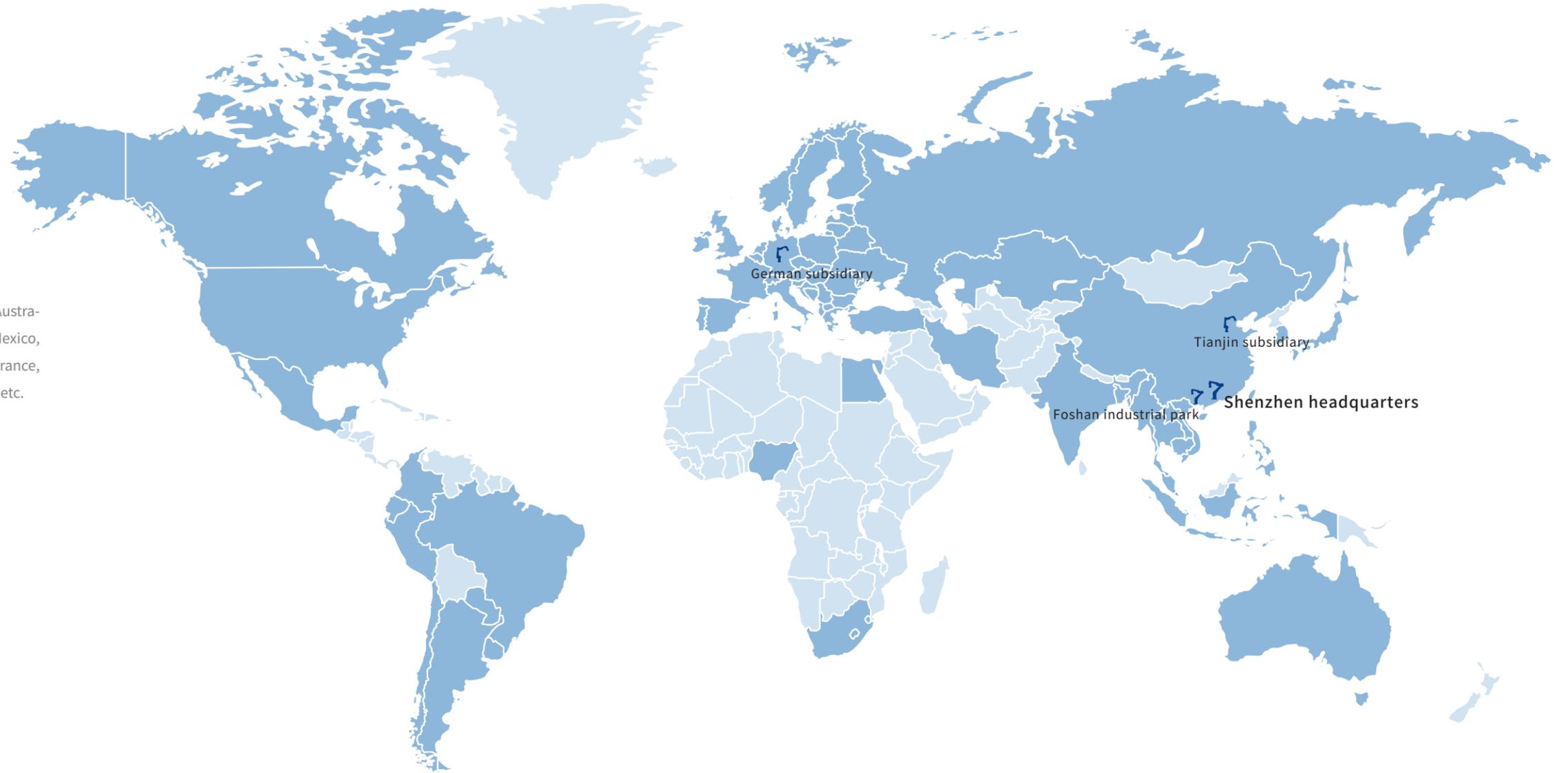
Global Service Network

Partners from more than 60 countries

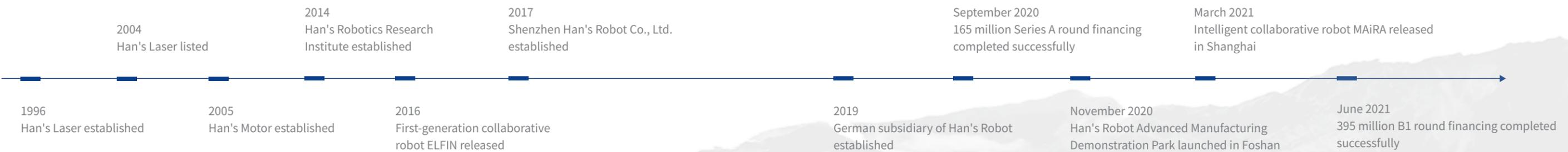
China, South Korea, Japan, Thailand, Singapore, Australia, New Zealand, the United States, Canada, Mexico, Brazil, Colombia, Argentina, Russia, Britain, France, Germany, Spain, the Netherlands, Lithuania, Italy, etc.

Top talents from 18+ countries & regions

200+ 200+ Employees
150+ 150+ Professional engineers
18+ Countries



Milestones





Han's Robot

Product Advantages



Han's Robot has been constantly exploring the breadth and depth for serving human by its self-developed leading collaborative robot technologies. The payload of the robots vary from 3kg to 18kg which can meet the requirements of various customers. Moreover, Han's Robot has developed products from the first generation 6-axis collaborative robots Elfin robot to the second-generation Elfin-P robot with higher performance, and has released 7-axis intelligent collaborative robots MAiRA in March 2021.



Each joint with a motion range of $\pm 360^\circ$

- High motion efficiency ✓
- More positions can be reached ✓
- Most flexible collaborative robot ✓
- Low power consumption ✓



Self-developed dual-joint modules

- Self-developed dual-joint modules ✓
- Unique arm design, optimized singularity points ✓
- Higher integration ✓
- Higher flexibility ✓

EtherCAT
EtherCAT bus communication

- Strong anti-interference ability ✓
- High communication frequency and fast speed ✓
- High safety, accurate motion trajectory ✓
- All joint data is open ✓



Self-developed of core components

- Completely self-developed core components from Han's Group ✓
- Complete set of motors, servo drive ✓
- Grating encoder, 6-dimensional force/torque sensor ✓
- Electromagnetic brake, high-speed inverter ✓



Innovative brake method

- The robot will automatically rebound and then stop when encounter any resistance. ✓
- Output force and power controlled within the safety range to ensure personnel safety. ✓
- Innovative brake design. The robot will be locked immediately in case of a sudden power failure or emergency stop during operation. It will not slide, fall or move at all ✓



IP66 protection rating

- Higher waterproof and dust-proof protection ✓
- Which is more suitable for harsher environments ✓
- And can avoid external objects and dust ✓
- Moreover, it can adapt to areas with various climates and humidity levels ✓



ISO class 5 cleanroom

- The surface cleanliness of the whole robot is excellent due to the excellent waterproof and dust-proof performance ✓
- Optimized structure of internal parts, low mutual friction, avoiding damage ✓
- Excellent sealing of the whole robot, without impurities intrusion ✓
- Automotive and aerospace industry standards, ensuring high quality ✓



More than 16 years of industrial experience

- Incubated from the Robotics Research Institute team of Han's Motor ✓
- More than 16 years experience in motors, servo drives and motion control ✓
- Long-term cooperation with famous universities at home and abroad ✓
- Dedicated to collaborative robot technologies and applications ✓



More open platform

- Open source ROS interface, which allows users to control the robot joints in real time through EtherCAT under the ROS environment ✓
- ROS platform, which greatly improves the robot's scalability. The robot can be controlled without an additional control box ✓
- Used for ROS teaching in colleges and universities ✓



Graphical control

- Graphical software design, intuitive, easy to understand, easy to operate ✓
- User-friendly interface logic design, easy to use ✓
- The software controls the robot with instant reactions, without delay, out of control and other symptoms ✓
- Remote control via touchscreen, excellent human-machine experience ✓



Han's Robot Plug & Play Tools



Adhering to the ecological concept of "all are friends in the world", Han's Robot has created a more complete and open collaborative ecosystem, and designed various IO and communication interfaces. These IO interfaces greatly expand the application scope of the robot and can support "plug and play" with most accessories in the industrial ecosystem, such as grippers, vision, and sensors, which can meet the needs of multiple scenarios such as loading and unloading, assembly, testing, handling, screw driving, grinding, spraying etc.

Grippers

	Robotiq		SMC		RobustMotion
	Onrobot		Schunk		HIWIN
	DH-Robotics		HITBOT		SRT

Force Sensor

	Link-touch		SRI		Onrobot
	ATI		Robotiq		Hypersen

Vision

	Micromatch		Basler		Cosmosvision
	Mech-Mind		Cognex		Seizet
	Keyence		Hikvision		

Scan code to join us

Han's Robot Partner Ecosystem
To build an open, shared and win-win industrial ecosystem!



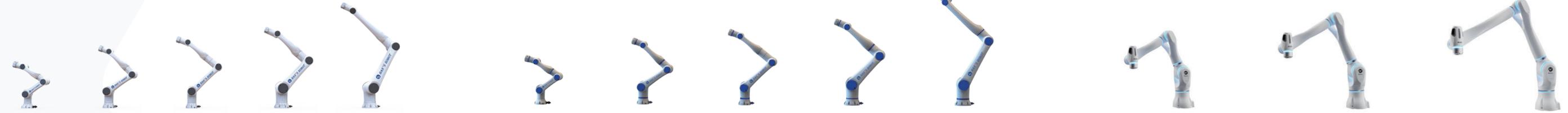
"POSS" Concept

The smartest body, the smartest brain:

Han's Robot believes that the characteristics of a good collaborative robot can be summarized as POSS. We are dedicated to the research and application expression of cutting-edge robotics technology, and the development of robots with the smartest body and the smartest brain.

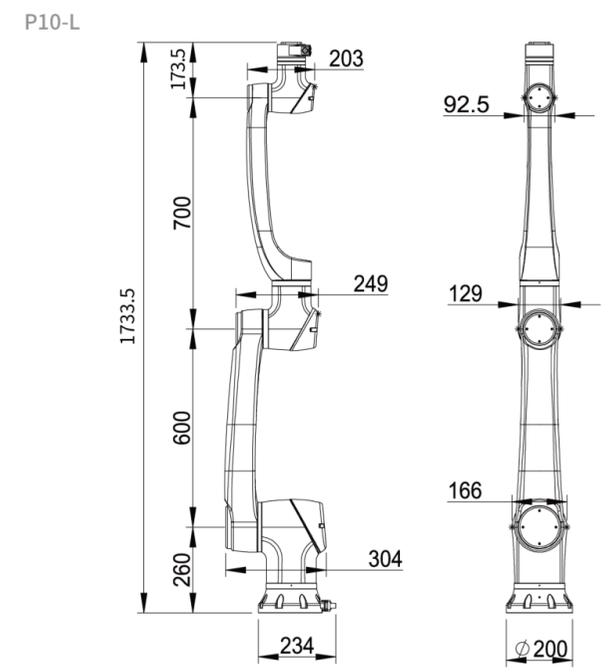
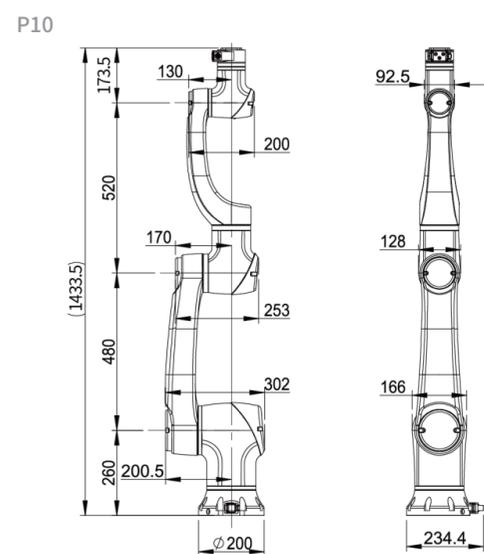
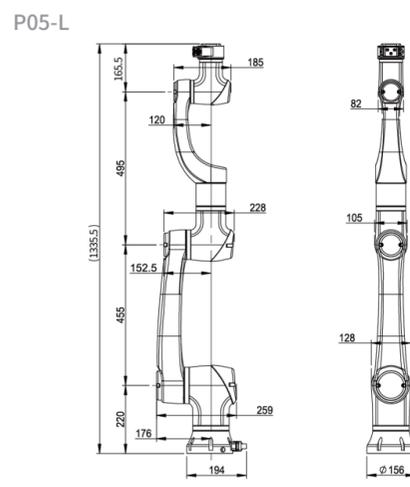
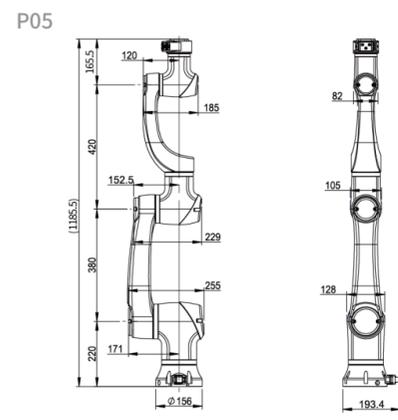
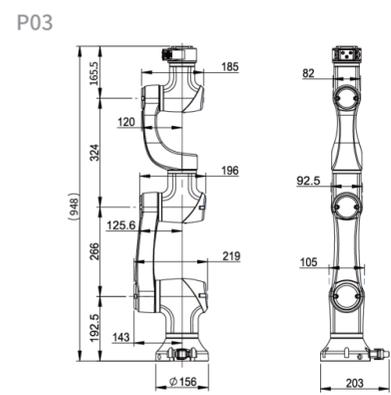
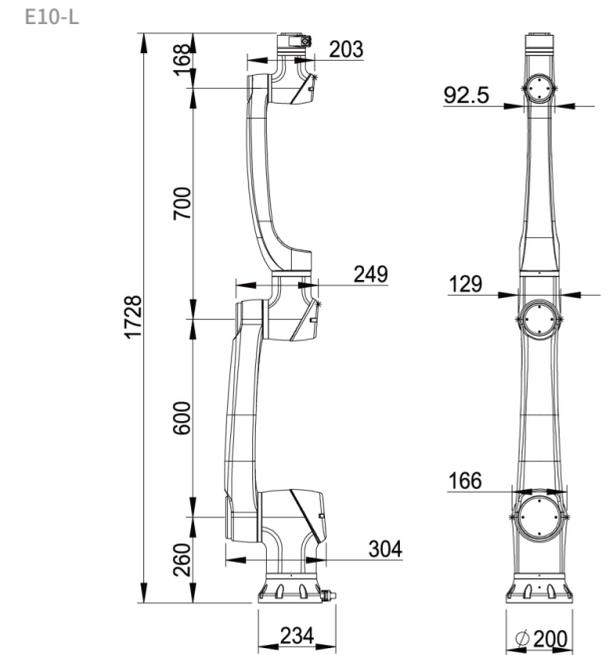
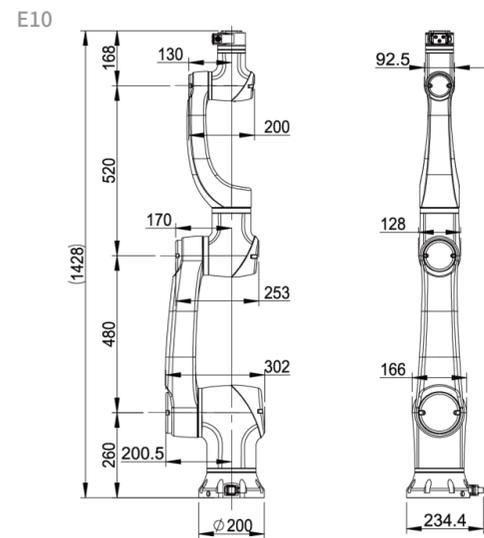
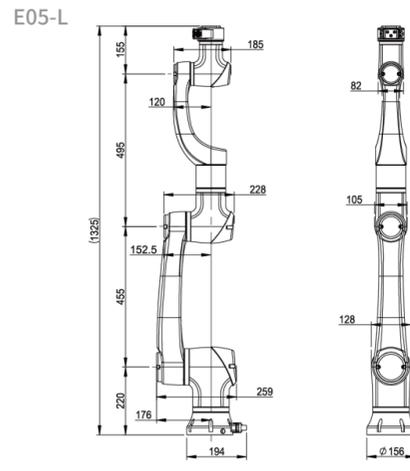
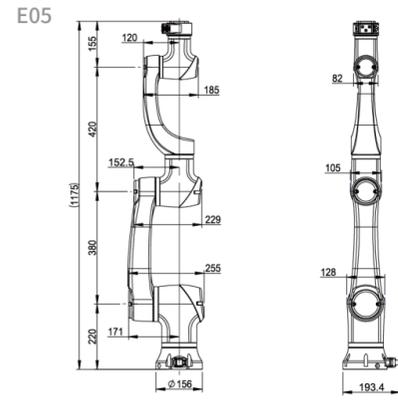
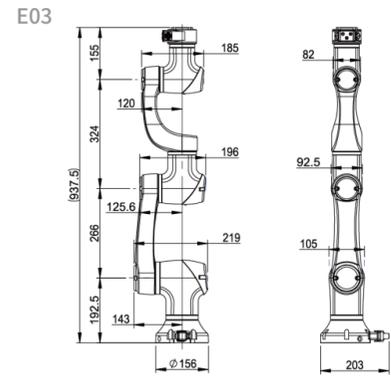


Overview



Model	E03	E05	E05-L	E10	E10-L	P03	P05	P05-L	P10	P10-L	MAiRA-ProS	MAiRA-ProM	MAiRA-ProL
Weight	17kg	23kg	24kg	40kg	42.5kg	18kg	24kg	25kg	42kg	45.5kg	53 kg (7-DOF) 49.5 kg (6-DOF)	55 kg (7-DOF) 51.5 kg (6-DOF)	56 kg (7-DOF) 52.5 kg (6-DOF)
Payload	4kg	6kg	5kg	12kg	12kg	3kg	5kg	4kg	10kg	8kg	15-18kg	12-14kg	8-11kg
Reach	590mm	800mm	950mm	1000mm	1300mm	590mm	800mm	950mm	1000mm	1300mm	1050mm	1400mm	1600mm
Power consumption	100W typical application	180W typical application	180W typical application	350W typical application	350W typical application	100W typical application	180W typical application	180W typical application	350W typical application	350W typical application	3.5kW typical application	3.5kW typical application	3.5kW typical application
Joint range	±360°					±360°					±360°		
Joint speed	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s	J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J2 120°/s J3-J4 135°/s J5-J6 180°/s	J1-J2 100°/s J3-J4 135°/s J5-J6 180°/s	J1-J2 120°/s J3-J4 150°/s J5-J6 200°/s J7 360°/s		
Tool speed	2m/s					2m/s					4.5m/s		
Repeatability	±0.03mm	±0.03mm	±0.03mm	±0.05mm	±0.1mm	±0.02mm	±0.03mm	±0.03mm	±0.05mm	±0.1mm	±0.01mm	±0.01mm	±0.01mm
Degrees of freedom	6					6					7		
Control box size	536*445*319mm					536*445*319mm					450*380*210mm		
End I/O port	Digital input: 3, digital output: 3, analog input: 2					Digital input: 3, digital output: 3, analog input: 2					—		
Control box I/O port	Digital input: 16, digital output: 16, analog input: 2, analog output: 2					Digital input: 16, digital output: 16, analog input: 2, analog output: 2					—		
I/O source	24V 2A					24V 2A					24V 600mA		
Communication	TCP/IP and Modbus					TCP/IP and Modbus					EtherCAT/FSoE, TCP/IP, USB3.0, GPIO, CAN Bus, Modbus		
Programming	Graphical programming, remote call interface					Graphical programming, remote call interface					Graphical programming, remote call interface		
IP rating	IP54					IP66					IP65		
Collaborative operation	10 advanced security configuration functions					10 advanced security configuration functions					Multiple advanced security configuration functions		
Main material	Aluminum alloy					Aluminum alloy					Aluminum alloy		
Working temperature	0-50°C					0-50°C					0-50°C		
Power input	200-240V AC, 50-60Hz					200-240V AC, 50-60Hz					100-240V AC, 50/60Hz, 3.2kW		
Cable	Cable to the control box: 5 m, cable to the teach pendant: 5 m					Cable to the control cabinet: 5 m, cable to the teach pendant: 5 m					Cable to the control cabinet: 5 m, cable to the teach pendant: 5 m		

Drawing





Han's Robot Product Details →



Elfin
collaborative
robot



Elfin-P
collaborative
robot



MAiRA
multi-sensing
intelligent
robot



Star
robot

Elfin Collaborative Robot

Overview

The Elfin 6-axis collaborative robot can be used in automated integrated production lines, assembly, picking, welding, grinding, spraing and other applications, and have been exported to more than 60 countries and regions. It adopts a unique double-joint module design, where one motion module contains two joints to form a unique kinematic structure, which not only differs from most collaborative robots in the market, but also provides more flexibility when working.



Why Elfin

Optimized Singularity

The unique arm design not only avoids the product homogeneity, but also reduces the singularity.



First dual-joint module design in China

The unique kinematic design enables the robot to have high flexibility. The highly integrated modular design minimizes the arm weight.



Highly Flexibility 6-DOF collaborative robot

The collaborative robot with 4/6-axis coaxial structure has almost reached the flexibility of 7-DOF robots



Modularity

All-in-one module of fully self-developed reducer, motor, encoder, drive and software



Industries

- Electronics
- Automotive
- Metal processing
- Semiconductor
- Education and research

Applications

- Loading and unloading
- Assembly
- Picking
- Welding
- Palletizing
- Glue dispensing
- Inspecting

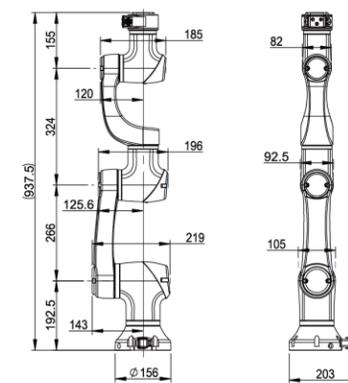
Technical Specifications



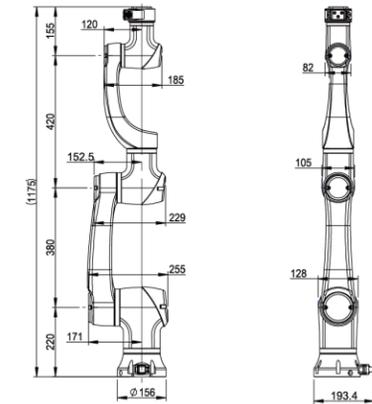
Model	E03	E05	E05-L	E10	E10-L
Weight	17kg	23kg	24kg	40kg	42.5kg
Payload	4kg	6kg	5kg	12kg	10kg
Reach	590mm	800mm	950mm	1000mm	1300mm
Power	100W typical application	180W typical application	180W typical application	350W typical application	350W typical application
Joint range	±360°				
Joint speed	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s	J1-J2 100°/s J3-J4 150°/s J5-J6 180°/s
Tool speed	2m/s				
Repeatability	±0.03mm	±0.03mm	±0.03mm	±0.05mm	±0.1mm
Degree of freedom	6				
Control box size	536*445*319mm				
End I/O port	Digital input: 3, digital output: 3, analog input: 2				
Control box I/O port	Digital input: 16, digital output: 16, analog input: 2, analog output: 2				
I/O Source	24V 2A				
Communication	TCP/IP and Modbus				
Programming	Graphical programming, remote call interface				
IP classification	IP54				
Collaborative operation	10 advanced security configuration functions				
Main material	Aluminum alloy				
Working temperature	0-50°C				
Power input	200-240V AC, 50-60Hz				
Cable	Cable to the control box: 5m; cable to the teach pendant: 5m				

Drawing

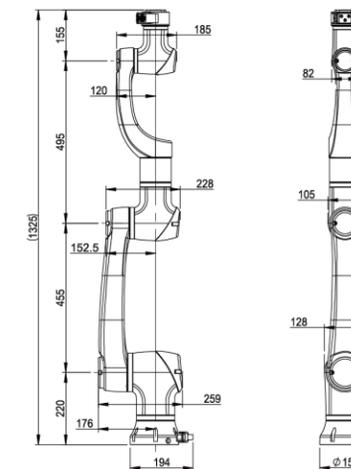
E03



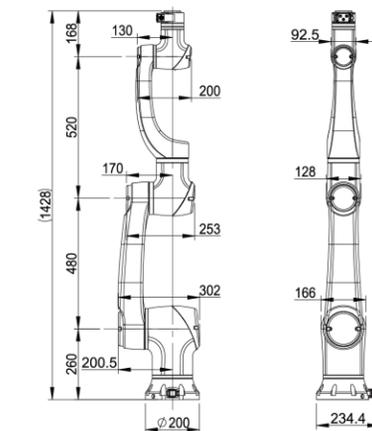
E05



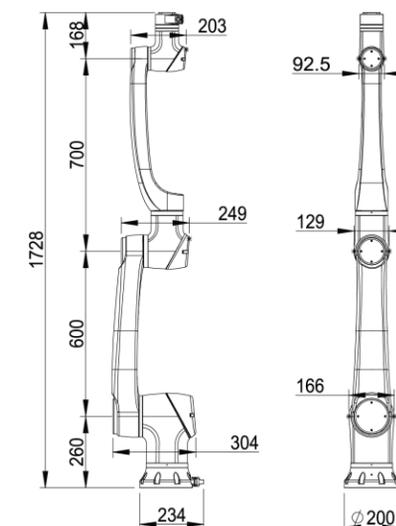
E05-L



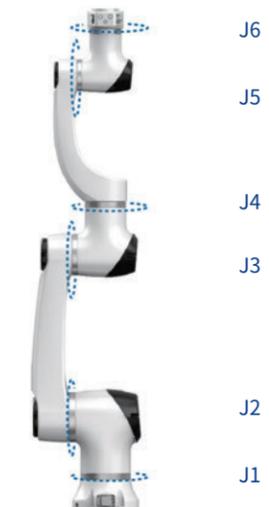
E10



E10-L



Joint motions:



Elfin-P Collaborative Robot

Overview

Elfin-P is a lightweight 6-axis collaborative robot developed based on Elfin that can be used in automated integrated production lines, assembly, picking, welding, grinding, spraying, dispensing, inspecting and other applications. The high repeatability and protection rating ensures it can be used freely in complex working environments.



Why Elfin-P

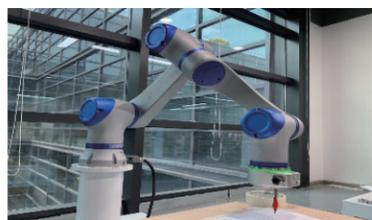
Higher protection rating

IP66 protection rating is designed to be dust-proof and waterproof, ensuring that it can be used freely in harsh environments such as oil and moisture



Faster response

The EtherCAT communication between the controller and each joint enables real-time control of the refresh frequency of 1000Hz for industry-leading trajectory accuracy control



Stronger anti-interference ability

Stronger electromagnetic compatibility, which ensures that the robot can still operate properly in a strong electromagnetic interference environment



High accuracy

The repeatability can reach ± 0.02 mm and it will not decrease with the wear of the reducer.



Industries

- Electronics
- Automotive
- Semiconductor
- Metal processing
- Education and research

Applications

- Loading and unloading
- Assembly
- Picking
- Welding
- Palletizing
- Dispensing
- Inspecting

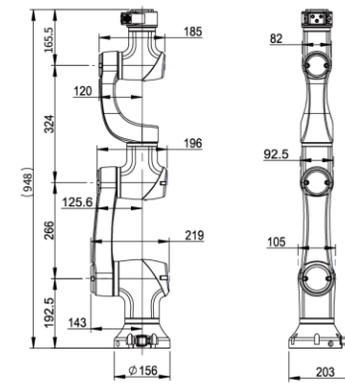
Technical Specifications



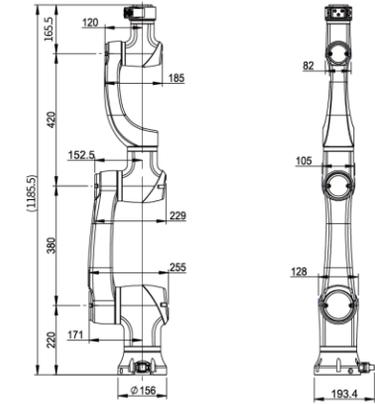
Type	P03	P05	P05-L	P10	P10-L
Weight	18kg	24kg	25kg	42kg	45.5kg
Payload	3kg	5kg	4kg	10kg	8kg
Reach	590mm	800mm	950mm	1000mm	1300mm
Power	100W typical application	180W typical application	180W typical application	350W typical application	350W typical application
Joint range	±360°				
Joint speed	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J4 180°/s J5-J6 200°/s	J1-J2 120°/s J3-J4 135°/s J5-J6 180°/s	J1-J2 100°/s J3-J4 135°/s J5-J6 180°/s
Tool speed	2m/s				
Repeatability	±0.02mm	±0.03mm	±0.03mm	±0.05mm	±0.1mm
Degree of freedom	6				
Control box size	536*445*319mm				
End I/O port	Digital input: 3, digital output: 3, analog input: 2				
Control box I/O port	Digital input: 16, digital output: 16, analog input: 2, analog output: 2				
I/O source	24V 2A				
Communication	TCP/IP and Modbus				
Programming	Graphical programming, remote call interface				
IP classification	IP66				
Collaborative operation	10 advanced security configuration functions				
Main material	Aluminum alloy				
Working temperature	0-50°C				
Power input	200-240V AC, 50-60Hz				
Cable	Cable to the control cabinet: 5m; cable to the teach pendant: 5m				

Drawing

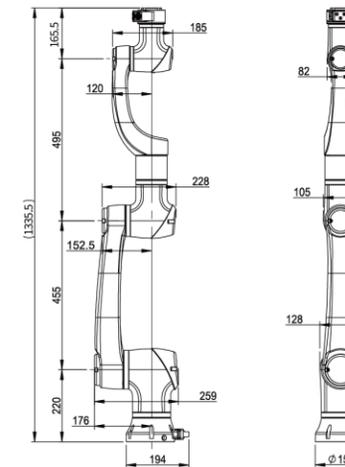
P03



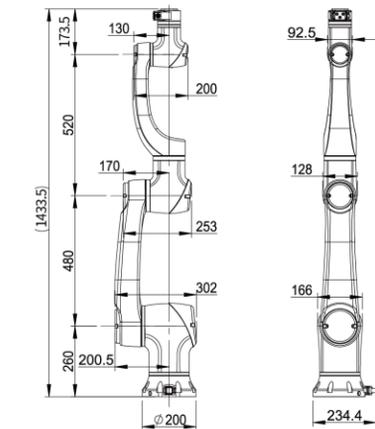
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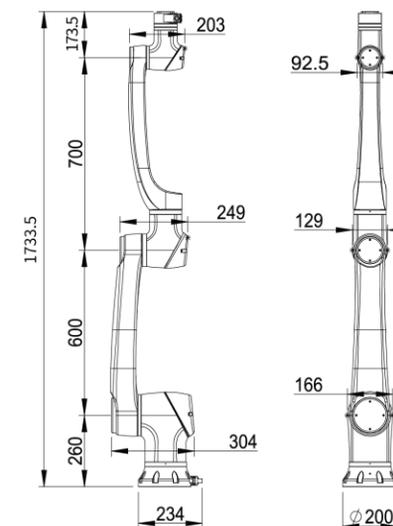
P05-L



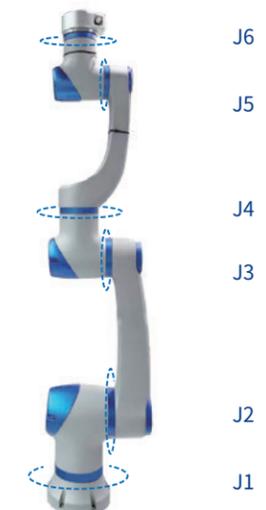
P10



P10-L



Joint motions:



MAiRA Multi-Sensing Intelligent Robot

Overview

With fully integrated novel sensors and an unprecedented integration of artificial intelligence in control systems and applications MAiRA is leading a new era of robots. The robust and rigid design combines the performance of a high-end machine with easy programming and infinite possibilities for interaction—both for beginners and experts. MAiRA tears down the boundaries between humans and machines and brings them closer together.



Industries

- Electronics
- Automobile
- Semiconductor
- Healthcare
- Aerospace

MAiRA-ProS
1050mm
15-18kg



MAiRA-ProM
1400mm
12-14kg



MAiRA-ProL
1600mm
8-11kg



Why MAiRA

3D visual sensing

With a novel 3D vision and a point cloud imaging processor, MAiRA can scan and generate 3D images of objects, spaces, and scenes sensitively and independently.



Voice recognition

You can collaborate with MAiRA by voice commands and conversations. It can keep your voice automatically so that you can be recognized at any time, which greatly improve the efficiency.



Top intelligent integration

Headend collection: HDM touchscreen buttons, 3D acoustic recognition technology of 360° panoramic microphone matrix, accurately response of 6-DOF electronic skin to gesture touch, 3D vision sensor, 6-DOF force-torque sensor...



Exquisite user experience

The touchscreen remote control is easy to use. The operation interface is intuitive and easy to understand, with zero learning effort and direct image visualization without programming.



Applications

- Loading and unloading
- Assembly
- Picking
- Welding
- Palletizing
- Dispensing
- Inspecting

Technical Specifications



Model	MAIRA-ProS	MAIRA-ProM	MAIRA-ProL
Weight	53 kg (7-DOF) 49.5 kg (6-DOF)	55 kg (7-DOF) 51.5 kg (6-DOF)	56 kg (7-DOF) 52.5 kg (6-DOF)
Payload	15-18kg	12-14kg	8-11kg
Reach	1050mm	1400mm	1600mm
Power	3.5kW typical application	3.5kW typical application	3.5kW typical application
Joint range	±360°		
Joint speed	J1-J2 120°/s J3-J4 150°/s J5-J6 200°/s J7 360°/s		
Tool speed	4.5m/s		
Repeatability	±0.01mm		
Degree of freedom	7		
Robot Mounting	Any angle		
IP classification	IP65		
Data, Media & Power	Complete internal wiring harness and air tube		
Status illumination	Seven colorful LED indicators		
Safety level	PLd Cat.3 / SIL3		

Sensor	
Vision	3D RGB-D camera
Torque/Force sensor	6-DOF F/T-Sensor in Flange
Guidance by Touch	Smart Sensitive 6-DOF Sensor Skin
Safety	Touchless Safe Human Detection(optional)
Sound	3D voice recognition sensor

TCP Connector Flange	
Hole pattern	DIN ISO 9409-1-50-7-M6
Compressed Air	3 x Push-Pull-Plug – 3mm OD
EtherCAT	M8 4-pin-A-F IEC 61076-2-104
GPIO	M8 8-pin-A-M IEC 61076-2-104
I/O power supply	24V 600mA

Movement

	Working Range	Maximum speed
A1	±360°	120°/Sec.
A2	±120°	120°/Sec.
A3	±270°	150°/Sec.
A4	±150°	150°/Sec.
A5	±270°	200°/Sec.
A6	±160°	200°/Sec.
A7	±360° / Infinite rotation	360°/Sec.

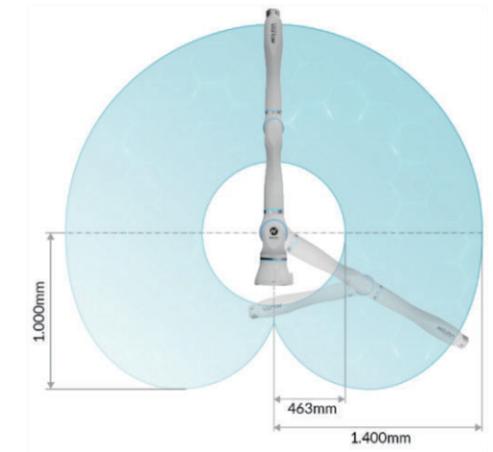
Software & Controller

Motion Controller	Real-time NR-Motion master
Machine Learning (ML) Kernel	ISmart application: voice control learning, action optimization
Open Architecture	3rd party Apps, Access to low level controllers & sensor data
Software Interface	Robots, sensors and AI SDKs
Safety Architecture	Safe Master & FSoE Communication
Safety Features	Safe position, speed, torque, limits



Control box

Dimensions	450 mm x 380 mm x 210 mm
Weight	25 kg
Power supply	100-240 VAC, 50/60 Hz, 3,2 kW
Interface	EtherCAT/FSoE, TCP/IP, USB 3.0, GPIO, CAN Bus, Modbus



Programming features

Smart GUI	NR easy programming interface
Fast programming	Shortcut buttons, voice control, gesture control, dynamic path and real-time recording
Human-computer interaction	Visual, voice and force feedback, facial recognition, motion tracking
Environment Visualization	3D CAD Data & Sensor Data



Teach pendant

Dimensions	285 mm x 228 mm x 95 mm
Resolution	1280 x 800
Display	10.5" touchscreen
Cable length	5 m
Usability	PAD is Detachable

Star Robot

Overview

Star robot is a movable manipulator that can pick and transport materials in work positions, which reduces the number of robots to be used and improves the flexibility of the production line. With Han's AGV, Han's six-axis collaborative robot, vision system, and force control gripping in robot system, start robot can confirm the location of the workpieces. It is mainly used in industries (such as electronics, metal products, auto parts, electricity, new energy, ships, aerospace), healthcare, family services, file management and other applications.



Features



Fast deployment

The environment map can be automatically generated based on natural trackless navigation technology, no need to do scene modification, so as to rapidly deploy the scheduling and planning services



Self-check

It can obtain the robot hardware and operating status in real time, which realizes self-check and fast fault diagnosis



Automatic charging

Star can automatically go back to charging pile for recharging, which ensures the robot to achieve 7x24 operation and high-frequency fast response



Intelligent scheduling

Schedule robots on a large scale based on self-developed architecture and intelligent planning algorithms, which ensures efficient system operation



High expansibility

It can efficiently connect to the enterprises' MES/WMS and information system, and can quickly carry application and function modules as required



Intelligent obstacle avoidance

Intelligently detect and identify obstacles, and actively stop and bypass obstacles, via the equipped sensors such as lidar and vision cameras



Dynamic stability

The power and load are positively auto-correlated within a safe range by using the proprietary core patent

Applications



Intelligent automatic distribution in motor workshops



Automatic loading and unloading on the dicing and splitting machine



Loading and unloading in intelligent workshops

Technical Specifications

Model	STAR-I	STAR-II	
Main body	Robot	E5 (6-axis collaborative robot, 5kg payload)	E10 (6-axis collaborative robot, 10kg payload)
	Vehicle	AGV (300kg load capacity)	AGV (600kg payload)
Basic performance	Dimensions (length x width x height)	1,100 x 650 x 745mm (size tolerance \pm 2mm)	
	Weight	460kg (including the vehicle weight)	
	Payload	50kg	
Running performance	Speed	1.5m/s	
	Operating speed	Forward: 1m/s; backward 0.3m/s	
	Radius of gyration	568mm	
	Gradeability	5°	
	Obstacle clearance height	10mm	
	Over seam width	30mm	
	Ground clearance	25mm	
	Walking channel width	Min 890mm	
	Revolving channel width	Min 1300mm	
	Site positioning precision	\pm 10mm	
Endurance performance	Battery capacity	51.2V40Ah lithium iron phosphate battery	
	Battery life	DOD \geq 80% 1,500 times, 0.5C charge 1C discharge (normal temperature)	
	Endurance time	8 hours, 1m/s, load 600kg	
External Interface	Charging method ¹	Automatic/Manual	
	Charging time	Charge to 95% in 1.3 hours	
External Interface ²	Power outlet	2CH DC51.2V1000W(40~57.6) 32 DC24V20W (regulated power supply) ³	
	Standard communication interface	One RS232 One CAN	
	I/O interface	CAN communication extension supported	
¹ Use an automatic charging pile. The charging time is 1.3h. ² For details about how to use the external interfaces, contact the robot to obtain the usage document. ³ DC24V, external power supply up to 20 W. If you require a higher power, you are advised to convert DC51.2N into DC24V.			



Han's Robot Applications

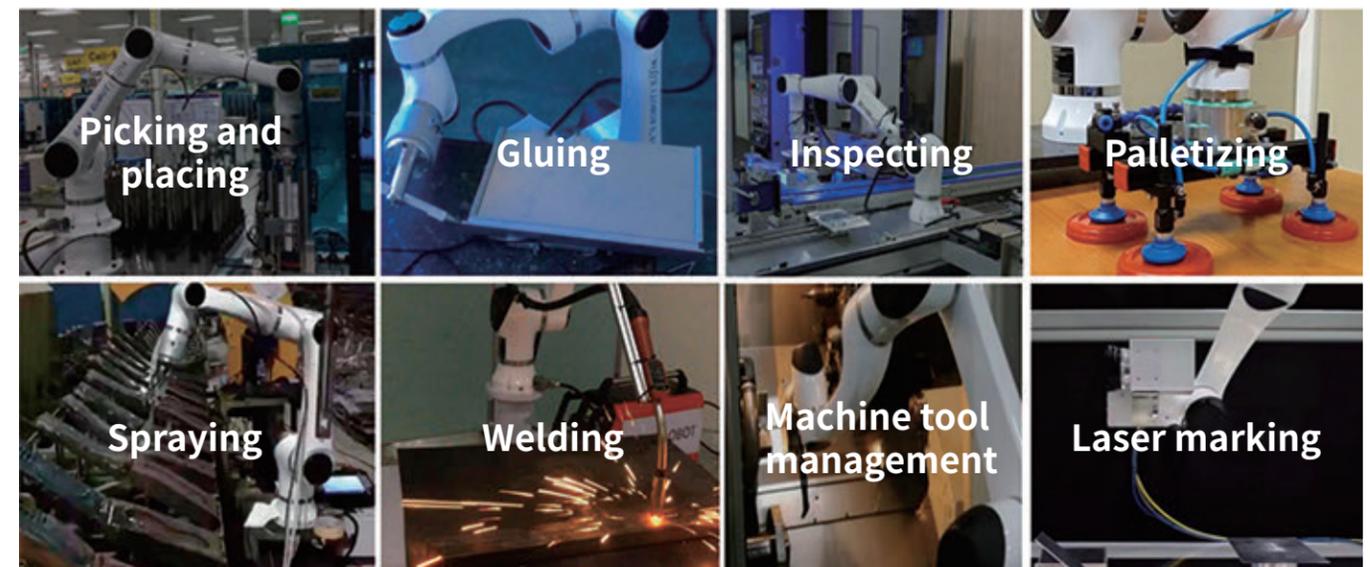


↑ Industry applications:

Han's Robot collaborative robots have been widely used in electronics, automotives, semiconductors, metal processing, new energy, pipeline inspection and other fields. Han's Robot uses robot technologies for collaboration in global intelligent manufacturing, which promotes productivity in all walks of life.

↓ Process applications:

Loading and unloading, welding, marking, assembling, polishing, pipeline handling, inspecting, gluing, picking, screwing, etc.



Electronics manufacturing industry Laser cutting

One robot is used for loading and unloading for four laser cutting machines at the same time. The four cutting machines are placed in pairs, and a 7-axis guide rail is used in the middle to realize the motion of the collaborative robot between the machines. A vision camera is integrated to the robot to realize the positioning for loading and unloading as the required unloading precision of the laser cutting machine is about 0.1 mm.

Space-Saving

The overall layout is compact which occupies a small area, and there is no need to do great changes to the original plant. Moreover, the equipment deployment is easy.

Easy to operate

It is easy to operate the collaborative robots. Customers can switch products or debug new products by themselves after simple training, which greatly reduces the cost of product replacement.



More scenarios: loading and unloading, inspecting, grinding, spraying, assembling, marking, etc.

Healthcare industry Remote ultrasound diagnosis and treatment

The remote ultrasonic diagnosis and treatment robot realizes remote consultation of experts in different places by using teleoperation technologies, which meets the increasingly demand for diagnosis resources in the grassroots hospitals.

Precision: The robot accurately reproduces the doctor's operating position and strength, which ensures the quality of ultrasound imaging;

Friendly: Gentle motion control, real-time pressure tracking control, to achieve a friendly patient experience comparable to professional examination methods;

Safe: Ensure the safety of human-computer interaction through high-level safety functions such as robot motion area limitation, inspection pressure protection, and collision protection;

Efficient: High-speed remote communication realizes high-definition ultrasound image transmission, and remote real-time control of robotic arms, which ensures the efficiency and precision of doctors' diagnosis;



More scenarios: drug packaging, test tube pickup and placing, sterilization, testing, surgical assistance, etc.

Automotive manufacturing industry Gluing for car lights

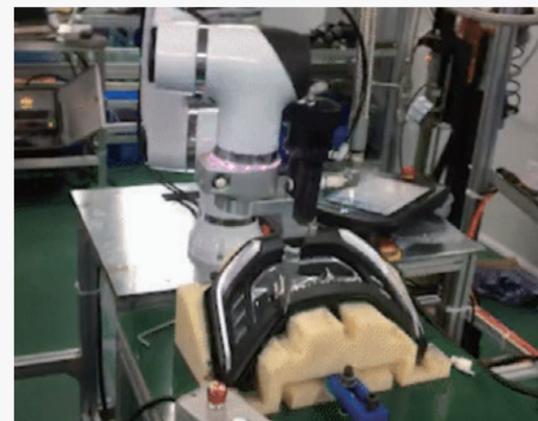
By adopting one-to-two structure integration, one cold glue device supplies can glue for two collaborative robots. The double-station free gluing improves the gluing efficiency and quality and avoids the impact on the personnel health, which greatly reduces labor and equipment costs.

Safe and flexible

High-precision linear gluing, harmless operation, improved yield rate.

Energy saving and low consumption

The cold glue does not require heating, which greatly reduces energy consumption.



More scenarios: loading and unloading, spraying, assembling, inspecting, picking, marking, etc.

Hybrid robot Distribution+ Loading and unloading

In this application, the robot moves intelligently in the same workshop to support multiple productions: Intelligent automatic distribution in the motor workshop project

Case features

Han's 6-axis collaborative robot integrated with an intelligent AGV can avoid obstacles, which is more suitable for narrow space environment, and can help customers to realize automated production without changes to the original equipment.

More scenarios: warehousing, packaging, assembling, testing, pickup, etc.



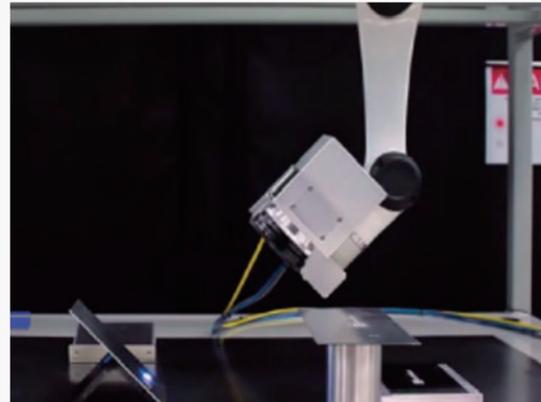
Metal processing industry Laser Marking

Han's marking robots can realize multi-directional automatic marking, from loading and unloading to marking, which meets the unmanned, automated, and flexible use requirements, improves the delivery efficiency, and reduces production costs.

Flexible and efficient Easy to operate

Realize flexible, efficient, multi-angle, multi-material free marking.

Graphical programming and robot program editing are simple and easy.



More scenarios: marking, rust removal, grinding, screwing, welding, etc.

Sanitary industry Spin welding

Solve the pain points of ultrasonic welding with high noise and inconsistent manual feeding pace
Less labor and higher efficiency, easy to operate, stable robot production



More scenarios: visual grasping, gate polishing, assembling, picking and placing, hot plate welding, loading and unloading, etc.

Semiconductor Industry Wafer handling

Han's hybrid robots interwork with wafer processing equipment to provide MES whole-factory automated wafer handling solutions, and fully independent IPR upper-computer scheduling system and planning.

Fast and robust

One robot is connected to five wafer processing devices for loading and unloading, and the efficiency is 68% higher than manual operation. The fully automated black light factory works automatically in a controllable manner. Multiple devices can be independently scheduled in 24-hour operation.



More scenarios: lithography, cleaning, etching, precipitation, equipment care, grinding, etc.

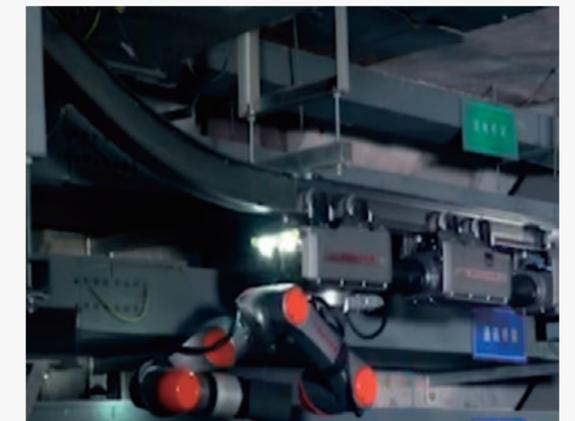
Pipeline inspection industry Pipeline equipment inspection

In this application, Han's Robot is integrated with various sensors to realize 24-hour visual automatic inspection in the pipeline. The 6-DOF joint design allows the robot to be better planned for complex motion paths, increases the monitoring scope and precision, and achieves no-blind-angle monitoring.

Diverse applications Less risks

Used in power, energy, petroleum, transportation, smart buildings, etc.

Less safety risks and labor costs compared with traditional manual inspections



More scenarios: electricity, energy, construction, transportation, minerals, marine

Education industry

VR training

1. VR industrial robot task training system based on virtual reality. It realizes multi-brand, multi-robot, multi-scene robot task operation training, including robot welding training, robot spraying training, robot casting training, robot palletizing training, robot loading and unloading training, and robot mobile phone assembly training.
2. Learn and master the operations of industrial robots through the VR robot system, and practical training of physical collaborative robots, which further deepens and consolidates the basic knowledge and skill training results of industrial robots, and greatly improves the teaching and training effects.



More scenarios: teaching platform, cyclic assembly line, mobile robot application, SCARA application, laser marking robot loading and unloading workstation, disassembly and installation of collaborative robot, robot integrated standard workstation

New retail industry

Milk tea robot

In this application, a new tea flagship store uses Han's robots in the beverage production area to collaborate in tea making, blending, and delivery, which adds value (such as freshness, attractiveness, and customer experience) to its service and image and greatly speeds up beverage production.

Fresh experience

One-click self-service, widely used in airports, hotels, restaurants, stations, shopping malls, and other places

Save kitchen labor

Less labor and higher efficiency, easy operation, convenient maintenance, short time period of cost recovery



More scenarios: massage, coffee latte, unmanned sales, etc.